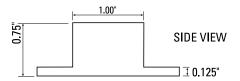
# Tilt Sensors

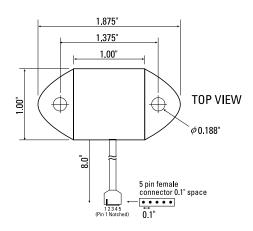
SOLID STATE, ANALOG SERIES

- ▼ Small, Low-Cost, Rugged
- ▼ Rapid Response
- ▼ ± 75° Range
- ▼ Fully Conditioned Analog Outputs

# **Applications**

- ▼ Scissor Lifts
- ▼ Static Platforms
- ▼ Survey Leveling Equipment
- ▼ Laser Leveling







### CXTA01, CXTA02

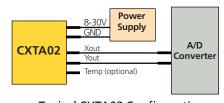
The CXTA single and dual axis analog tilt sensors offer resolution, accuracy, and fast response in an inexpensive, easy-to-use package. The CXTA series design centers on a highly stable silicon micro-machined capacitive inclination sensor element. The CXTA series is fully signal conditioned with high level analog output(s), and optional analog temperature signal.

Micro-machined devices, perfected in automotive safety applications, offer several distinct advantages over fluid, electrolytic, and pendulumbased sensors. Like other solid-state devices, they are more reliable than their mechanical counterparts. In a package smaller than many pendulum or fluid raw sensing elements, completely integrated electronics

eliminate the need for external components.

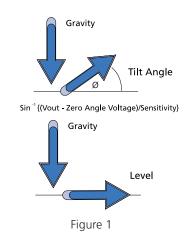
Unlike other micro-machined devices, the CXTA Series maintains its accuracy and stability over temperature: < 2° of arc over the range 0° to 70° C. The output can be user corrected for temperature with the T option, yielding accuracy to within  $\pm$  0.5° over the angular range.

A typical configuration using CXTA sensors is shown below. Each module is factory calibrated, tested and includes a calibration sheet. The module can be securely attached using screws or adhesive. The CXTA is available in a standard nylon or high temperature aluminum package.



Typical CXTA02 Configuration

Specifications	CXTA01	CXTA02	Remarks	
Specifications	CAIAOI	CATAOL	Remarks	
Performance				
Linear Angular Range (°)	± 20	± 20		
Full Angular Range (°)	± 75	± 75		
Angular Resolution (° rms)	0.05	0.05		
Sensitivity - small angles (mV/°)	35 ± 2	35 ± 2	Actual value provided with Sensor	
Sensitivity Drift (%/°C)	0.01	0.01		
Zero Angle Voltage (Volts)	2.5 ± 0.15	2.5 ± 0.15	Actual value provided with Sensor	
Zero Angle Drift (mV/°C)	1.0	1.0	Typical	
Zero Angle Drift <sup>(0</sup> / <sup>0</sup> C)	0.2	0.2	Typical	
Non-Linearity (°)	< 0.4	< 0.4	Over ± 20° not including Arcsine Error	
Bandwidth (Hz)	125	125		
Settling Time (sec)	0.2	0.2		
Alignment (°)	± 1	± 1	Typical	
Cross-axis Sensitivity (%)	< 5	< 5	Inclusive of alignment error	
Environment				
Storage Temperature (°C)	-55 to +85	-55 to +85	Nylon Package	
Operating Temperature (°C)	-40 to +85	-40 to +85	Nylon Package	
Storage Temperature (°C)	-55 to +105	-55 to +105	-AL High Temperature Package	
Operating Temperature (°C)	-40 to +105	-40 to +105	-AL High Temperature Package	
Non-Operating Vibration (g rms)	10	10	20-2 kHz random	
Shock (g)	2000	2000	1 ms, half sine	
Electrical				
Supply Voltage (VDC)	8 - 30	8 - 30	Unregulated	
Current (mA)	4	8		
Physical				
Size (Nylon Package)	.75 x 1.875 x 1	5 x 1.875 x 1.00" (1.91 x 4.763 x 2.54 cm)		
(Aluminum Package)	.95 x 2.00 x 1.	x 2.00 x 1.20" (2.41 x 5.08 x 3.05 cm)		
Weight (Nylon Package)	1.38 oz (43 gm	1.38 oz (43 gm)		
(Aluminum Package)	2.09 oz (65 gm	5 gm)		





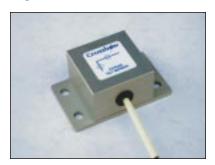
Specifications subject to change without notice

## **Principle of Operation**

The CXTA Series Tilt Sensors use a micro-machined acceleration sensing element with a DC response to measure inclination relative to gravity. The response of the tilt sensor depends on the magnitude of gravity parallel to the sensor element. The output of the tilt sensor will be an offset voltage plus the voltage response proportional to the amount of gravity measured by the sensor.

# **Using the CXTA Sensor**

The voltage response of the CXTA is proportional to the sine of the tilt angle.



Optional Aluminum Package

Accurately measuring tilt angle involves solving the equation shown in the bottom of Figure 1. Clearly to solve this equation the Zero Angle Voltage and Sensitivity must be determined prior to use. Crossbow provides this information on a calibration sheet with its CXTA products.

For angles less than 20°, the sine function can be approximated by a linear relationship between the Vout and the tilt angle in radians. Thus the equation for angle in degrees is:

 $180/\pi$  \* [(Vout - Zero Angle Voltage)/Sensitivity]

The  $180/\pi$  factor changes the angle from radians to degrees. When the tilt angle is less than  $20^\circ$ , the error from linear approximation will be less than 1%. This is convenient when you don't have or want the computing power to calculate an inverse sine function.

Pin	Color	Function			
1	Red	Power			
2	Black	Ground			
3	White	Pitch			
4	Yellow	Roll			
5	Green	Temp			

Pin Diagram

#### Ordering Information

Model	Axes	Linear Range	Full Range	Resolution	
CXTA01	Х	± 20°	± 75°	0.05°	
CXTA02	X,Y	± 20°	± 75°	0.05°	
OPTIONS					
-T	Temperature Sensor Internal				
-AL	High Temperature Aluminum Package				

CALL FACTORY FOR OTHER CONFIGURATIONS

If ordering options, please specify Model followed by the regulator option and then the package option, e.g. CXTA01-T-AL